# Computable Execution Traces & Algorithms

Declan Thompson

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# Outline

What are algorithms?

2 Computable Execution Traces

- Finite control computability
- Carrying out trace sets

3 Algorithms as trace sets

# What are algorithms?

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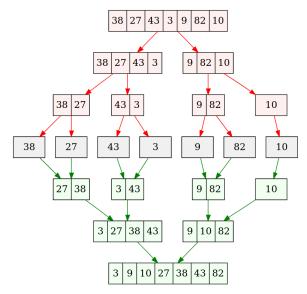
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Mergesort sorts a given list of numbers by first dividing them into two equal halves, sorting each half separately by recursion, and then combining the results of these recursive calls—in the form of the two sorted halves—using the linear time algorithm for merging sorted lists that we saw in Chapter 2. [7, p. 210]



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#### Equivalence class approach

Algorithms as equivalence classes under some equivalence relation. *Dubious that any adequate equivalence relation exists.* 

#### Generalised programs

Allow arbitrary operations and objects in programs. *Language dependent, and over-determined.* 

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  - 5 Show extensional equivalence with other accounts → Church-Turing Thesis

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### Computable execution traces (cont.)

In all cases, we get a model which takes input and moves through a (possibly infinite) sequences of stages. This gives a set of *execution traces*, built from the bottom up.

$$\mathrm{Run}_{\mathfrak{M}} = \begin{cases} ([|B], [1|B], [|1B], [|BB]) \\ ([|1], [1|B], [11|B], [1|1B], [|1BB]) \\ ([|1B1], [1|B1], [11|1], [111|B], [11|1B], [1|1BB]) \\ \vdots \end{cases}$$

The focus is on what can be computed, not the way the computation proceeds.

#### Motivating question

What is required for a given set of sequences to be the execution trace set of some computable process?

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 $(\![|\mathsf{B}],[\mathsf{1}|\mathsf{B}],[|\mathsf{1}\mathsf{B}],[|\mathsf{B}\mathsf{B}]]\!)[0,3)=(\![|\mathsf{B}],[\mathsf{1}|\mathsf{B}]\!)$ 

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• If  $\sigma[-1] = \tau[0]$  then  $\sigma \circ \tau = (\sigma[0], \sigma[1], \dots \sigma[-1], \tau[1], \tau[2], \dots)$ .

 $(\![|\mathsf{B}],[\mathsf{1}|\mathsf{B}],[|\mathsf{1}\mathsf{B}]\!)\circ(\![\mathsf{1}|\mathsf{B}],[|\mathsf{B}\mathsf{B}]\!)=(\![|\mathsf{B}],[\mathsf{1}|\mathsf{B}],[|\mathsf{1}\mathsf{B}],[|\mathsf{1}\mathsf{B}]\!)$ 

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 $(\![|B], [1|B], [|1B]\!]) \circ (\![1|B], [|BB]\!]) = (\![|B], [1|B], [|1B], [|BB]\!])$ 

• 
$$\mathbf{F} \circ \mathbf{G} = \{ \sigma \circ \tau \mid \sigma \in \mathbf{F}, \ \tau \in \mathbf{G} \}.$$

• Q is a test if  $|\sigma| = 1$  for all  $\sigma \in Q$ .  $F \circ Q = \{\sigma \in F \mid \sigma[-1] \in Q\}$ 

P is an operation if  $|\sigma| = 2$  for all  $\sigma \in P$ .  $F \circ P = \{\sigma \mid \sigma[0, -1) \in F, (\sigma[-2], \sigma[-1]) \in P\}$ 

### Idea: Assemble tasks from primitive operations

- Q is a *test* if  $|\sigma| = 1$  for all  $\sigma \in Q$
- P is an operation if  $|\sigma| = 2$  for all  $\sigma \in P$
- Q ∘ P is a guarded operation
- $\blacksquare \ \mathbf{F} \circ \mathbf{Q} \circ \mathbf{P} = \{ \sigma \mid \sigma[0, -1) \in \mathbf{F}, \ \sigma[-2] \in \mathbf{Q}, \ (\![\sigma[-2], \sigma[-1]]\!] \in \mathbf{P} \}$
- Classical accounts utilise a finitary control mechanism.
- This gives an equivalence relation on stages of a computation, similar to a bisimulation:

   σ[0,1) ⇔ τ[0,1) for all σ, τ ∈ F

   if σ[0, α + 1) ⇔ τ[0, α + 1) then "the same thing" happens in each

# Control Equivalence

 Assume we're given a set of tests q and a set of operations p: the actions we can use. Assume we're given a set of tests q and a set of operations p: the *actions* we can use.

$$\begin{split} \mathrm{TT}_{\mathbf{a}} &:= \{ \langle \! \left[ \mathbf{u} | \mathbf{a} \mathbf{v} \right] \! \right\} \mid \mathbf{u}, \mathbf{v} \in \Gamma^* \} \\ \mathrm{TM}_{\mathbf{a},\mathsf{R}} &:= \{ \langle \! \left[ \mathbf{u} \mathbf{b} | \mathbf{c} \mathbf{v} \right], \left[ \mathbf{u} \mathbf{b} \mathbf{a} | \mathbf{v} \right] \! \right\} \mid \mathbf{u}, \mathbf{v} \in \Gamma^* \ \mathbf{b}, \mathbf{c} \in \Gamma \} \\ \mathrm{TM}_{\mathbf{a},\mathsf{L}} &:= \{ \langle \! \left[ \left[ \mathbf{u} \mathbf{b} | \mathbf{c} \mathbf{v} \right], \left[ \mathbf{u} | \mathbf{b} \mathbf{a} \mathbf{v} \right] \! \right\} \mid \mathbf{u}, \mathbf{v} \in \Gamma^* \ \mathbf{b}, \mathbf{c} \in \Gamma \} \\ \mathfrak{q} &= \{ \mathrm{TT}_{\mathbf{a}} \mid \mathbf{a} \in \Gamma \} \\ \mathfrak{p} &= \{ \mathrm{TM}_{\mathbf{a},\mathsf{R}}, \mathrm{TM}_{\mathbf{a},\mathsf{L}} \mid \mathbf{a} \in \Gamma \} \end{split}$$

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Set  $\sigma \leftrightarrows \tau$  iff they correspond to the same internal state of  $\mathfrak{M}$ .

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- $\sigma[0,1) \leftrightarrows \tau[0,1)$  for all  $\sigma, \tau \in \mathbf{F}$ .

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 $(\![|\mathsf{B}]\!) \leftrightarrows (\![|\mathsf{1}]\!) \leftrightarrows (\![|\mathsf{1B1}]\!) \leftrightarrows \ldots$ 

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- $\sigma[0,1) \leftrightarrows \tau[0,1)$  for all  $\sigma, \tau \in F$ .
- If  $\sigma \leftrightarrows \tau$  then "the same thing" should happen at each.
  - How to capture this?

- - **1** Every guarded operation in  $\mathfrak{F}_C$  gets applied to every  $\sigma \in C$ ; and
  - 2 If a guarded operation is successfully applied to σ and τ, the results are equivalent under ⇔.

- There is a construction set of guarded operations *𝔅<sub>C</sub>* ⊆ 𝑘 × 𝑘 such that
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$\delta$	1	В
<b>s</b> 0	$ \begin{array}{c} \langle 1, R, \textbf{\textit{s}}_0 \rangle \\ \langle 1, R, \textbf{\textit{s}}_1 \rangle \\ \langle B, L, \textbf{\textit{s}}_3 \rangle \end{array} $	$\langle 1, R, \mathbf{s}_1 \rangle$
$s_1$	$\langle 1, R, \textbf{s}_1 \rangle$	$\langle \mathtt{B}, \mathtt{L}, \emph{s}_2  angle$
$s_2$	$\langle { t B}, { t L}, { t s}_3  angle$	_
$s_3$	—	_

$$\mathfrak{F}_{C} = \begin{cases} \{\langle \mathrm{TT}_{1}, \mathrm{TM}_{1,\mathsf{R}} \rangle, \langle \mathrm{TT}_{\mathsf{B}}, \mathrm{TM}_{1,\mathsf{R}} \rangle \} & s = s_{0} \\ \{\langle \mathrm{TT}_{1}, \mathrm{TM}_{1,\mathsf{R}} \rangle, \langle \mathrm{TT}_{\mathsf{B}}, \mathrm{TM}_{\mathsf{B},\mathsf{L}} \rangle \} & s = s_{1} \\ \{\langle \mathrm{TT}_{1}, \mathrm{TM}_{\mathsf{B},\mathsf{L}} \rangle \} & s = s_{2} \\ \emptyset & s = s_{3}. \end{cases}$$

$$([|1B11], [1|B11], [11|11]) \hookrightarrow ([|1B11], [1|B11], [11|11], [111|1], [1111|B]) (s_1)$$

Take an equivalence class C under  $\leftrightarrows$ .

- There is a construction set of guarded operations *𝔅<sub>C</sub>* ⊆ 𝑘 × 𝔅 such that
  - **1** Every guarded operation in  $\mathfrak{F}_C$  gets applied to every  $\sigma \in C$ ; and
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<b>s</b> 3	_	_
𝔩 <sub>C</sub> =	$\begin{cases} \emptyset \\ \emptyset \\ \{TT_B\} \\ \{TT_1, TT_2\} \end{cases}$	$s = s_0$ $s = s_1$ $s = s_2$ $r_B \}  s = s_3.$

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## Control Equivalence

### Definition (Control Equivalence)

Let q be a set of tests and p of operations. Let F be a task. A control equivalence  $\leftrightarrows$  on F under q and p is an equivalence relation on F satisfying: Starting State  $\sigma[0,1) \leftrightarrows \tau[0,1)$  for all  $\sigma, \tau \in F$ . Construction For each  $C \in F / \leftrightarrows$  there is a construction set  $\mathfrak{F}_C \subseteq \mathfrak{q} \times \mathfrak{p}$  such that both: Composition  $\{\sigma \in F \mid \sigma[0,-1) \in C\} = \bigcup_{\langle Q,P \rangle \in \mathfrak{F}_C} C \circ Q \circ P$ ; and Consistency if  $\langle Q,P \rangle \in \mathfrak{F}_C$  then  $C \circ Q \circ P \subseteq D$  for some  $D \in F / \leftrightarrows$ . Halting For each  $C \in F / \leftrightarrows$  there is a halting set  $\mathfrak{G}_C \subseteq \mathfrak{q}$  such that  $C \cap F = \bigcup_{Q \in \mathfrak{G}_C} C \circ Q$ .

#### Definition (Trace set)

A *trace set* for q and p is a pair  $A = (F, \leftrightarrows)$ , where F is a task and  $\leftrightarrows$  is a control equivalence on F under q and p.

### Proposition

For every task F over  $\mathfrak{D}$  there is a test set  $\mathfrak{e}$ , an operation set  $\mathfrak{w}$  and a control equivalence  $\leftrightarrows$  such that  $A = (F, \leftrightarrows)$  is a trace set for  $\mathfrak{e}$  and  $\mathfrak{w}$ .

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### Definition (Finite control computable)

A trace set A for q and p is *finite control computable* if  $A \not \hookrightarrow_A$  is finite, q and p are finite, and every  $Q \in q$  and  $P \in p$  is computable.

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#### Theorem

If  $\mathfrak{M} = \langle S, \Gamma, \delta, s_0 \rangle$  is a Turing machine then  $\operatorname{Run}_{\mathfrak{M}}$  is finite control computable.

### Is every FCC trace set the trace set of some Turing machine?

No!

- **1** FCC allows arbitrary computable tests and operations
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  - **1** For every  $\sigma \in A$  and  $\alpha < |\sigma|$ ,  $\sigma[\alpha] = [\mathbf{u}|\mathbf{v}]$  for some  $\mathbf{u}, \mathbf{v} \in \Gamma^*$ ; and
  - 2 For every  $u, v \in \Gamma^*$  there is a unique  $\sigma \in A$  with  $\sigma[0] = [u|v]$ ; and
  - **3** A is fully deterministic  $(\sigma[0] = \tau[0] \text{ implies } \sigma = \tau)$ .

Then there is a Turing machine  $\mathfrak{M} = \langle S, \Gamma, \delta, s_0 \rangle$  such that  $\operatorname{RuN}_{\mathfrak{M}} = A$  iff A is finite control computable.

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Can we do better? Can we allow arbitrary computable tests and operations?

## Expansion mapping

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Define a function h mapping prefixes of the original sequence to prefixes of the expanded sequence.

$$\begin{split} h(([|1B11])) &= ([|1B11]) \\ h(([|1B11], [11|11])) &= ([|1B11], [1|B11], [11|11]) \\ h(([|1B11], [11|11], [111|1B])) &= ([|1B11], \dots [111|1B]) \end{split}$$

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### Expansion Mapping

 $\mathbf{F} \ll \mathbf{G} \text{ if there is an injective } h: \mathbf{F} \to \mathbf{G} \text{ such that } \sigma \text{ is a subsequence of } h(\sigma) \text{ and } h(\mathbf{F}) = \mathbf{G}.$ 

### Example

Take  $\operatorname{PRIMES}$ , enumerating all prime in increasing order:

 $\{([11|B], [111|B], [11111|B], [111111|B], \ldots)\}$ 

Take  $\mathfrak{M} = \langle \{s\}, \{1, B\}, \delta, s \rangle$  with  $\delta(s, 1) = \delta(s, B) = \langle 1, R, s \rangle$ .

 $\{(\![|B],[1|B],[11|B],[111|B],[1111|B],\ldots)\}$ 

Two requirements:

- **1** We need to be able to recover the original task from the expanded task.
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### Definition (Carrying out)

We say A is *carried out* by B if there is an expansion mapping *h* from A to B such that  $C \in [A]/{\leftrightarrows_A}$  iff  $h(C) \in [B]/{\leftrightarrows_B}$ .

#### Theorem

Let  $A = (F, \leftrightarrows)$  be a trace set for q and p such that A is finite control and fully deterministic; q and p are both finite and Turing computable; there is a finite alphabet  $\Gamma$  such that

- 1 for every  $\sigma \in A$ ,  $\sigma[0] = [u|v]$  for some  $u \in \Gamma^*, v \in \Gamma^+$ ;
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Then there is a Turing machine  $\mathfrak{M}$  such that  $\operatorname{Run}_{\mathfrak{M}}$  carries out A.

#### Theorem

Let A be a trace set and  $\mathfrak{M} = \langle S, \Gamma, \delta, s_0 \rangle$  be a Turing machine. If  $\operatorname{Run}_{\mathfrak{M}}$  carries out A then A is finite control computable.

# Outline

What are algorithms?

2 Computable Execution Traces

- Finite control computability
- Carrying out trace sets

3 Algorithms as trace sets

Idea: Model algorithms as trace sets.

"Functionalism about functions"

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 Allow arbitrary domains and operations

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#### **1** Ask me for details about:

- Encoding: changing the domain over which a trace set is defined.
- Resolution: removing ambiguity from a trace set; introducing tie-breakers.
- Implementation: increasing the level of specification; the relationship between programs and algorithms.
- Computable functions vs. algorithms.

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- Resolution: removing ambiguity from a trace set; introducing tie-breakers.
- Implementation: increasing the level of specification; the relationship between programs and algorithms.
- Computable functions vs. algorithms.
- 2 Ask me to ramble about:
  - Trace sets with arbitrary tasks (not just tests and operations)
  - Recursive algorithms
  - Concurrent/parallel computation
  - Interactive algorithms
  - Transfinite sequences
  - Probabilistic algorithms
  - Complexity theory

Thank you!

Thank you!

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